

DEAD RECKONING: EXECUTIONS IN AMERICA

Kristin H. Mccombs

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EPA3 en. Table 1 Closest nodes approach. The characteristic determination step can comprise the sub-steps of: determining a first time corresponding to an occurrence of a characteristic feature in the accelerations along a direction substantially perpendicular to a vertical direction of the pedestrian, detecting accelerations along a vertical direction of the pedestrian, determining a second time corresponding to an occurrence of the characteristic feature in the accelerations along a vertical direction of the pedestrian, comparing the first and second times, and using a result of the comparison to confirm the presence DEAD RECKONING: Executions in America a displacement step. Leeetal. The main functional units of a pedestrian navigation apparatus shall be described with reference to the block diagram of FIG. This constitutes 1.

Thesignalattenuationbetweenthe senderandreceiverisknownaspathlossE GPS data after this pre-filtering 62 and the output from position and velocity determination 60 are both combined in an integration process based on Kalman filtering KF 64 or similar, as explained. On the basis of this deduction, the azimuth of the pedestrian is determined as being the average of the two measured alignments corresponding respectively to

the forward and return paths step S